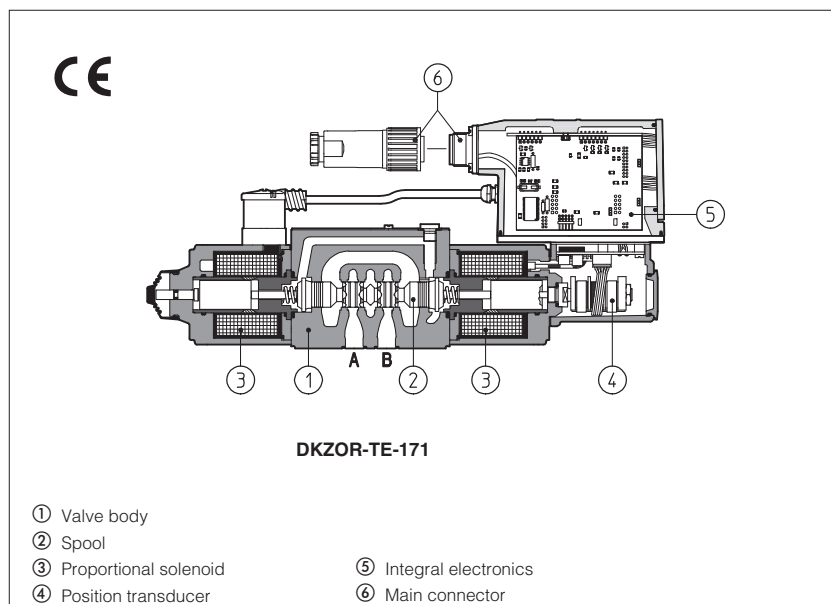


Proportional directional valves type DHZO-TE and DKZOR-TE

direct operated, with position transducer, ISO 4401 size 06 and 10



1 MODEL CODE

DHZO	- TES	- PS	- 0	7	1	- S	5	/	*	/	**	/	*
<div>DHZO = size 06 DKZOR = size 10</div> <div>T = with position transducer TE = as T with integral analog electronics TES = with digital electronics obsolete (4)</div> <div>Communication interfaces (only for TES) PS = Serial BC = CANopen BP = PROFIBUS DP</div> <div>Valve size 0 = ISO 4401 size 06 1 = ISO 4401 size 10</div> <div>Configuration, see section 3 5 = external plus central position, spring centered 7 = 3 position, spring centered</div> <div>Spool overlapping in central position, see section 3 0 = zero overlapping (0 to 5 % spool stroke) (1) 1 = P,A,B,T positive overlapping (20% of spool stroke) 2 = P,A,B,T positive overlapping with A-B draining (3) 3 = P positive overlapping (20% of spool stroke); A, B, T, negative</div> <div>Spool type (regulating characteristics) L = linear; S = progressive; D = differential-progressive (as S, but with P-A = Q, P-B = Q/2) Q = linear spool, for alternate P/Q controls (2) V = differential-progressive, for alternate P/Q controls (3)</div> <div>Spool size: 14, 1, 2, 3, 5, 9 = see section 3</div>		<div>Seals material: omit for NBR (mineral oil & water glycol) PE = FPM</div> <div>Series number</div> <div>Hydraulic options, see section 4: B = solenoid, integral electronics and position transducer at side of port A Y = external drain Electronics options, for -TE execution see section 7: F = fault signal I = current reference input and monitor (4÷20 mA) Q = enable signal Z = enable, fault and monitor signals (12 pin connector) Electronics options, for -TES execution see section 9: I = current reference input and monitor (4÷20 mA) Z = double power supply, enable fault and monitor signals (12 pin connector) Special options for -TES execution see section 9: SF = additional closed loop force control, with two remote pressure transducers SL = additional closed loop force control with one remote load cell SP = additional closed loop pressure control with one remote pressure transducer C = current feedback interface for transducer(s) only for options /SF, /SL, /SP</div>											

Notes: (1) For zero overlapping spool 0L3, 0L5, 0D5, the valve offset position (with switch-off power supply) is 1 ÷ 6% P-B/A-T
 (2) Only for DKZOR-S5 the spool overlapping type 2 provides the same characteristic of type 1, but in central position the internal leakages from P to A and B are drained to tank, avoiding the drift of cylinders with differential areas.
 (3) The spool type Q and V are specific for alternate P/Q controls and they can be used in combination with option /S* of digital integral drivers (see section 13.1, 14.1 and G212), or digital axis controllers type Z-RI-TEZ (see tab. F230) or Z-ME-KZ (see tab. G340)
 (4) This execution of TES digital valves is obsolete and no more available. For new execution of TES digital valves, see table FS165 with position spool overlap and FS168 with zero spool overlap

2 ELECTRONIC DRIVERS

Valve model	-T	-TE	-TES	-TES / SF, SL, SP
Drivers model	E-ME-T	E-RI-TE	E-RI-TES	E-RI-TES/SF, SL, SP
Data sheet	G140	G200	G210	G212

Note: For power supply and communication connector see section 16 and 18

DHZO-T* and DKZOR-T* are proportional valves, direct operated, with LVDT position transducer, which provide both directional and non-compensated flow control according to the electronic reference signal.

They operate in association with electronic drivers, see section 2, which supply the proportional valves with proper current to align valve regulation to the reference signal supplied to the electronic driver.

They are available in different executions:

- -T, with integral position transducer ④;
- -TE, -TES as -T plus analog (TE) or digital (TES) integral electronics ⑤.

The 4-way spool ②, sliding into a 5-chambers body ①, is directly operated by solenoids ③ and it is controlled in closed loop position by means of the LVDT position transducer ④

The integral electronics ⑤ ensures factory presetting, fine functionality plus valve-to-valve interchangeability and simplified wiring and installation.

The electronic main connector ⑦ is fully interchangeable for -TE and -TES executions.

Standard 7 pin main connector is used for power supply, analog input reference and monitor signals.

12 pin connector is used for options /K, /Z and /S*.

The special /S* options add a closed loop control of pressure (/SP) or force (/SF and /SL) to the basic closed loop spool position one.

Following communication interfaces ⑥ are available for the digital -TES execution:

- -PS, Serial communication interface for configuration, monitoring and firmware updating through Atos PC software
- -BC, CANopen interface
- -BP, PROFIBUS DP interface

The valves with -BC and -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The coils are fully plastic encapsulated (insulation class H) and the valves have antivibration, antishock and weather-proof features.

Mounting surface: ISO 4401 sizes 06 and 10.

Max flow respectively up to 50 l/min and 130 l/min with valve differential pressure $\Delta p = 30$ bar, see table 3.

Max pressure = 350 bar for DHZO;
315 bar for DKZOR.

3 HYDRAULIC CHARACTERISTICS (based on mineral oil ISO VG 46 at 50 °C)

<p>Hydraulic symbols</p>														
Valve model	DHZO-T*								DKZOR-T*					
Spool overlapping	1, 3	1, 3	1, 3	1, 3	0	0	1, 3	3	1, 3	0	0	2	1, 3	3
Spool type and size	L14	L1	S2	S3, L3, D3	L3	L5, D5	S5, L5, D5	Q5, V9	S3, L3, D3	L3	L5, D5	S5	S5, L5, D5	Q5, V9
Pressure limits [bar]	ports P, A, B = 350; T = 210 (250 with external drain /Y)								ports P, A, B = 315; T = 210 (250 with external drain /Y)					
Max flow (1) [l/min]														
at $\Delta p = 10$ bar (P-T)	1	4,5	8	17			28	30	45			75		
at $\Delta p = 30$ bar (P-T)	2	8	14	30			50	52	80			130		
at $\Delta p = 70$ bar (P-T)	3	12	21	45			74	80	120			170		
Response time (2) [ms]	< 15								< 20					
Hysteresis [%]	$\leq 0,2\%$								$\leq 0,2\%$					
Repeatability [%]	$\pm 0,1\%$								$\pm 0,1\%$					
Thermal drift	zero point displacement < 1% at $\Delta T = 40^{\circ}C$													

Notes:

- For version DHZO-TE and DKZOR-TE, configuration /B, see the notes at sections 13.1 and 14.1
 - Above performance data refer to valves coupled with Atos electronic drivers, see sections [2].
 - The flow regulated by the directional proportional valves is not pressure compensated, thus it is affected by the load variations. To keep constant the regulated flow under different load conditions, modular pressure compensators are available (see tab. D150).
- (1) For different Δp , the max flow is in accordance to the diagrams in sections 13.2 and 14.2
 (2) 0-100% step signal

4 HYDRAULIC OPTIONS

4.1 Option /B Solenoid (for valve configuration *5*), integral electronics and position transducer at side of port A. For version -T and -TE see section 13.1 and 14.1

4.2 Option /Y External drain advisable when the valve is used in double flow path, see section 13.5 and 14.5. Option /Y is mandatory if the pressure in port T exceeds 160 bar.

5 GENERAL NOTES

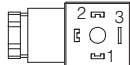
DHZO and DKZOR proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive).

Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

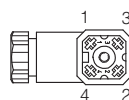
The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-892).

6 CONNECTIONS FOR -T EXECUTION

SOLENOID POWER SUPPLY CONNECTOR	
PIN	Signal description
1	SUPPLY
2	SUPPLY
3	GND



POSITION TRANSDUCER CONNECTOR	
PIN	Signal description
1	OUTPUT SIGNAL
2	SUPPLY -15 V _{DC}
3	SUPPLY +15 V _{DC}
4	GND



7 ANALOG INTEGRAL DRIVERS -TE - OPTIONS

Standard driver execution provides on the 7 pin main connector:

- Power supply** - 24V_{DC} must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to the driver power supply. Apply at least a 10000 $\mu F/40$ V capacitance to single phase rectifiers or a 4700 $\mu F/40$ V capacitance to three phase rectifiers
- Reference input signal** - analog differential input with ± 10 V_{DC} nominal range (pin D, E), proportional to desired valve spool position
- Monitor output signal** - analog output signal proportional to the actual valve's spool position with ± 10 V_{DC} nominal range

Following options are available to adapt standard execution to special application requirements:

7.1 Option /F

It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 V_{DC}, normal working corresponds to 24 V_{DC}.

7.2 Option /I

It provides the 4÷20 mA current reference and monitor signals instead of the standard ± 10 V_{DC}

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

7.3 Option /Q

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24V_{DC} on the enable input signal.

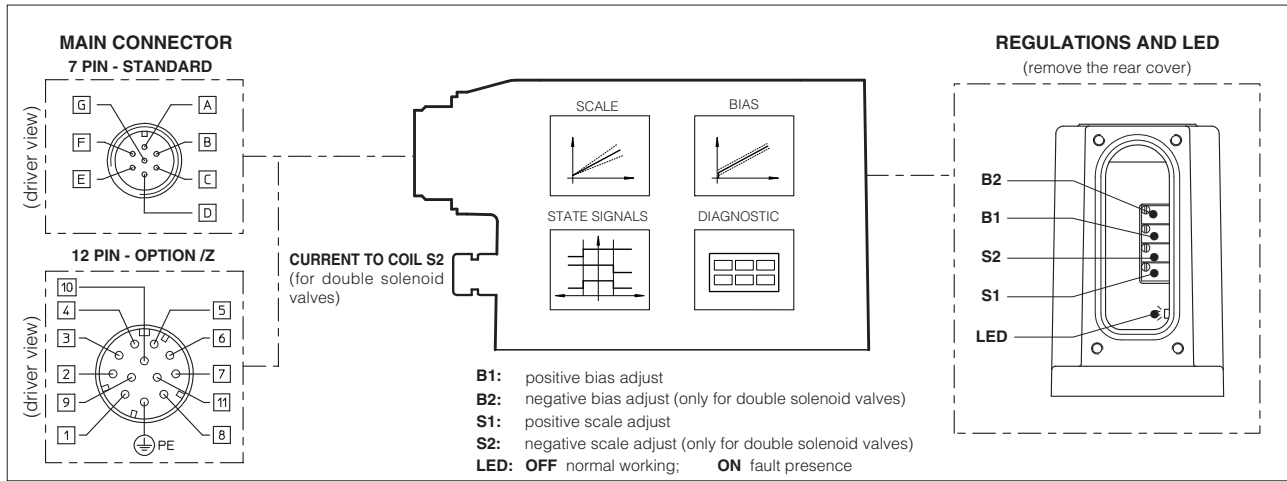
7.4 Option /Z

This option includes /F and /Q features, plus the Monitor output signal.

When the driver is disabled (0 V_{DC} on enable signal) Fault option is forced to 0 V_{DC}.

7.5 Possible combined options: /FI, /IK and /IZ

8 ANALOG INTEGRAL DRIVERS -TE - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



8.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V+	Power supply 24 Vdc for solenoid power stage and driver logic	Input - power supply
B	2	V0	Power supply 0 Vdc for solenoid power stage and driver logic	Gnd - power supply
C ⁽¹⁾	7	AGND	Ground - signal zero for MONITOR signal (for standard, /Z option)	Input - analog signal
	3	ENABLE	Enable (24 Vdc) or disable (0 Vdc) the driver (for /Q and /Z options)	Input - on/off signal
D	4	INPUT+	Reference analog differential input: ± 10 Vdc maximum range (4 \div 20 mA for /I option)	Input - analog signal
E	5	INPUT -	For single solenoid valves the reference input is 0 \div +10 Vdc (4 \div 20 mA for /I option) For double solenoid valves the reference input is ± 10 Vdc (4 \div 20 mA for /I option)	
F ⁽²⁾	6	MONITOR	Monitor analog output: ± 10 Vdc maximum range (4 \div 20 mA for /I option)	Output - analog signal
	11	FAULT	Fault (0V) or normal working (24V) (for /F and /Z options)	Output - on/off signal
-	8	R_ENABLE	Repeat Enable - output repetition of Enable input	Output - on/off signal
-	9	NC	do not connect	Output - on/off signal
-	10	NC	do not connect	Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing	

Notes

(1) with /Q option ENABLE signal replaces AGND on pin C; MONITOR signal is referred to pin B

(2) with /F option FAULT signal replaces MONITOR on pin F.

- A minimum time of 50ms to 100ms have be considered between the driver energizing with the 24 Vdc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

9 DIGITAL INTEGRAL DRIVERS -TES - OPTIONS

Standard driver execution provides on the 7 pin main connector:

- Power supply** - 24Vdc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to each driver power supply. Apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.
- Reference input signal** - analog differential input with ± 10 Vdc nominal range (pin D,E), proportional to desired valve spool position
- Monitor output signal** - analog output signal proportional to the actual valve's spool position with ± 10 Vdc nominal range

Following options are available to adapt standard execution to special application requirements:

9.1 Option /I

It provides 4 \div 20 mA current reference and monitor signals instead of the standard ± 10 V.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

9.2 Option /Z

It provides on the 12 pin main connector the following additional features:

Logic power supply

Separated power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

Enable Input Signal

To enable the driver, supply 24Vdc on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active.

Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 \div 20mA input, etc.). Fault presence corresponds to 0 Vdc, normal working corresponds to 24Vdc (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

9.3 Options /SP, /SF and /SL

These options add the closed loop control of pressure (/SP) or force (/SF and /SL) to the basic functions of proportional directional valves: a dedicated software alternates pressure (force) and valve's spool position controls depending on the actual hydraulic system conditions.

A dedicated connector is available for the additional transducers that are required to be interfaced to the valve's driver (1 pressure transducer for /SP, 2 pressure transducers for /SF or 1 load cell for /SL).

Main 12 pin connector is the same as /Z option plus two analog signals specific for the pressure (force) control: one for reference (pin 7) and one for monitor (pin 8).

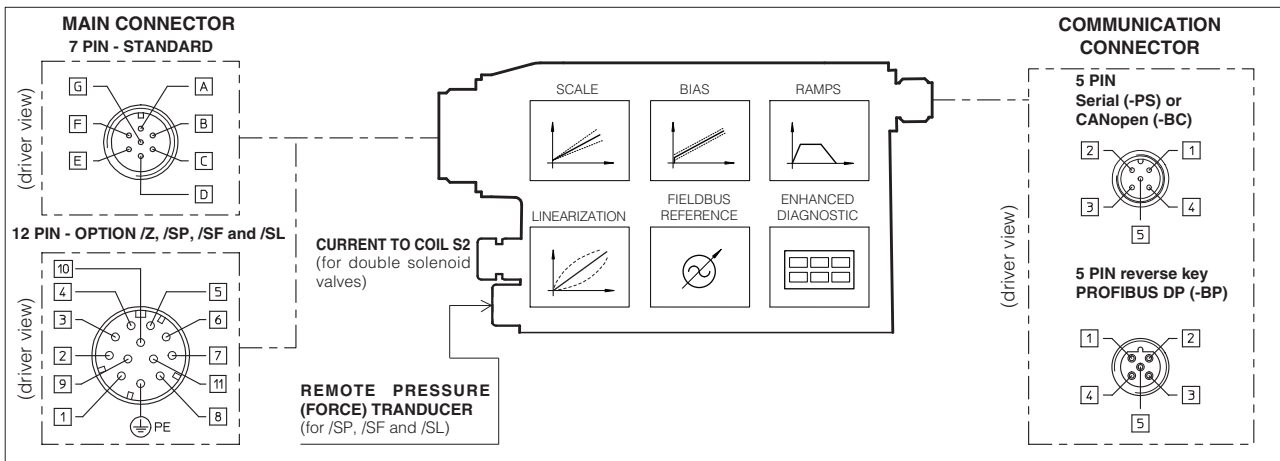
For further details please refer to the driver technical table **G212**.

9.4 Options /C

Options /CSP, /CSF and /CSL are available to connect pressure (force) transducers with 4 \div 20mA current output signal.

9.5 Possible combined options: /ISP, /ISF, /ISL, /CSP, /CSF, /CSL, /CISP, /CISF, /CISL and /IZ

10 DIGITAL INTEGRAL DRIVERS -TES - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



10.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V+	Power supply 24 V _{dc} for solenoid power stage (and for driver logic on 7 pin connection)	Input - power supply
B	2	V0	Power supply 0 V _{dc} for solenoid power stage (and for driver logic on 7 pin connection)	Gnd - power supply
-	3	ENABLE	Enable (24 V _{dc}) or disable (0 V _{dc}) the driver	Input - on/off signal
D	4	INPUT+	Reference analog input: ± 10 V _{dc} maximum range (4 \div 20 mA for /I option) For single solenoid valves the reference input is 0 \div +10 V _{dc} (4 \div 20 mA for /I option) For double solenoid valves the reference input is ± 10 V _{dc} (4 \div 20 mA for /I option) standard: differential input; /Z option: common mode INPUT+ referred to AGND	Input - analog signal
E	-	INPUT -		
C	5	AGND	Ground - signal zero for MONITOR signal signal zero for INPUT+ signal (only for /Z option)	Gnd - analog signal
F	6	MONITOR	Monitor analog output: ± 10 V _{dc} maximum range (4 \div 20 mA for /I option)	Output - analog signal
-	7	NC	do not connect (pressure/force input for /SP, /SF and /SL options, see 9.3)	
-	8	NC	do not connect (pressure/force monitor for /SP, /SF and /SL options, see 9.3)	
-	9	VL+	Power supply 24 V _{dc} for driver logic	Input - power supply
-	10	VLO	Power supply 0 V _{dc} for driver logic	Gnd - power supply
-	11	FAULT	Fault (0V) or normal working (24V)	Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing	

Note: A minimum time of 300 to 500 ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

10.2 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION CONNECTORS

-PS Serial			-BC CANopen		-BP PROFIBUS DP	
PIN	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	data line and termination Signal zero
4	RS_RX	Valves receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)
5	RS_TX	Valves transmitting data line	CAN_L	Bus line (low)	SHIELD	

11 SOFTWARE TOOLS

The driver configuration and parameters can be easily set with the Atos E-SW programming software, available in three different versions according to the driver's communication execution: E-SW-PS (Serial), E-SW-BC (CANopen) and E-SW-BP (PROFIBUS DP).

For a more detailed description of software interface, PC requirements, adapters, cables and terminators, please refer to technical table G500.

Programming software, must be ordered separately:

E-SW-* (mandatory - first supply) = Dvd including E-SW-* software installer and operator manuals; it allows the registration to Atos digital service

E-SW-*-N (optional - next supplies) = as above but not allowing the registration to Atos digital service

On first supply of the E-SW-* software, it is required to apply for the registration in the Atos download area: www.download.atos.com.

Once the registration is completed, the password will be sent by email.

The software remains active for 10 days from the installation date and then it stops until the user inputs his password.

With the password you can also download, in your personal area, the latest releases of the Atos software, manuals, drivers and configuration files.

12 MAIN CHARACTERISTICS OF PROPORTIONAL DIRECTIONAL VALVES

Assembly position	Any position	
Subplate surface finishing	Roughness index Ra 0,4 - flatness ratio 0,01/100 (ISO 1101)	
Ambient temperature	-20°C \div +70°C for -T execution; -20°C \div +60°C for -TE and TES executions	
Fluid	Hydraulic oil as per DIN 51524 ... 535 for other fluids see section [1]	
Recommended viscosity	15 \div 100 mm ² /s at 40°C (ISO VG 15 \div 100)	
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μ m ($\beta_{10} \geq 75$ recommended)	
Fluid temperature	-20°C +60°C (standard seals and water glycol) -20°C +80°C (/PE seals)	
Valve model	DHZO-T*	DKZOR-T*
Coil resistance R at 20°C	3 \div 3,3 Ω	3,8 \div 4,1 Ω
Max. solenoid current	2,6 A	3 A
Max. power	35 Watt	40 Watt
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account	
Protection degree (CEI EN-60529)	IP65 for -T execution; IP67 for -TE and -TES executions	
Duty factor	Continuous rating (ED=100%)	

13 DIAGRAMS FOR DHZO (based on mineral oil ISO VG 46 at 50 °C)

13.1 Regulation diagrams

- | | |
|--|--------|
| 1 = linear spool | L14 |
| 2 = linear spool | L1 |
| 3 = progressive spool | S2 |
| 4 = linear spool | L3 |
| 5 = progressive spool | S3, D3 |
| 6 = linear spool, zero overlapping | OL3 |
| 7 = linear spool | L5 |
| 8 = linear spool, zero overlapping | OL5 |
| 9 = progressive spool | S5, D5 |
| 10 = progressive spool, zero overlapping | OD5 |

Note:

Hydraulic configuration vs. reference signal for double solenoid valves (also for option /B)

Reference signal $0 \div +10 \text{ V}$
 $12 \div 20 \text{ mA}$ $P \rightarrow A / B \rightarrow T$

Reference signal $0 \div -10 \text{ V}$
 $4 \div 12 \text{ mA}$ $P \rightarrow B / A \rightarrow T$

Hydraulic configuration vs. reference signal for mono solenoid valves **option /B**

Reference signal $0 \div +10 \text{ V}$
 $12 \div 20 \text{ mA}$ $P \rightarrow B / A \rightarrow T$

11 = linear spool Q5

Q5 spool type is specific for alternate P/Q controls and it can be used in combination with /S* option of digital integral drivers, see tab. G212, or digital position controllers type Z-RI-TEZ (see tab. G330) or Z-ME-KZ (see tab. G340).

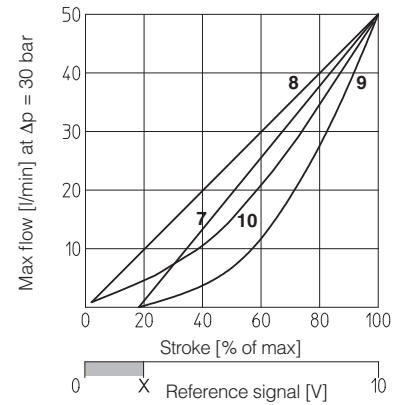
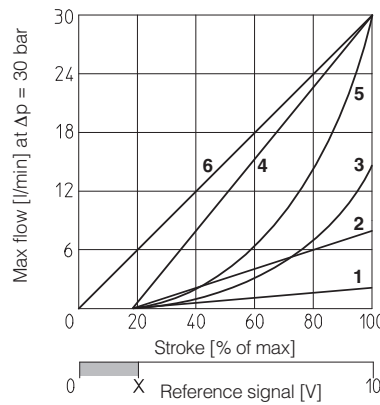
It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers. The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.

12 = differential - progressive spool V9

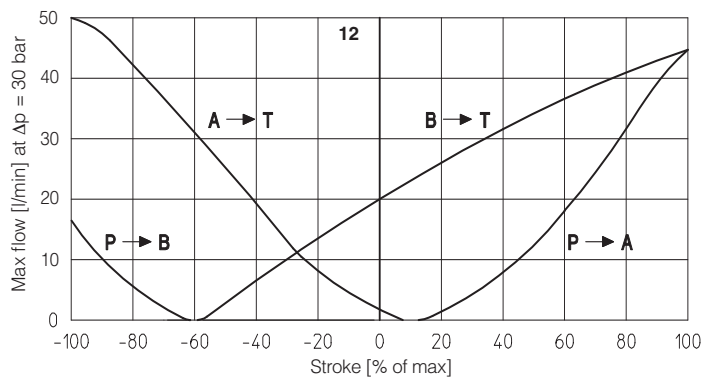
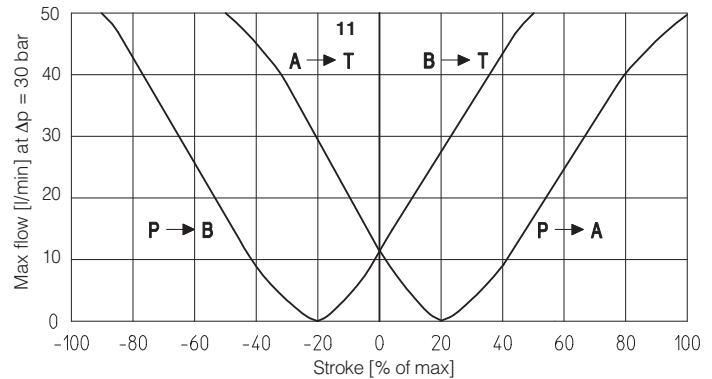
V9 spool type is specific for alternate P/Q controls and it can be used in combination with /S* option of digital integral drivers, see tab. G212, or digital position controllers type Z-RI-TEZ (see tab. G330) or Z-ME-KZ (see tab. G340).

This spool is specially designed to manage the whole injection cycle in plastic machinery, thanks to the following specific features:

- strong meter-in characteristic to allow the pressure control in A port during the holding pressure (P-A) and the plasticizing (A-T) phases
- safety central position (A-T/B-T) to depressurize the actuator chambers
- large A-T and B-T flow capability, required during the plasticizing phase, to discharge big volumes from high differential injection cylinders with low pressure drops and permitting the contemporary oil suction from tank



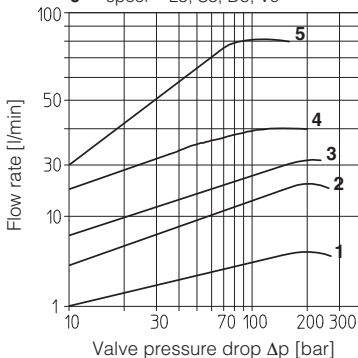
X = Threshold for bias activation depending to the valve type and amplifier type



13.2 Flow /Δp diagrams

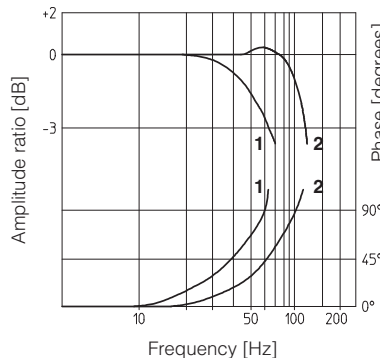
stated at 100% of valve stroke

- | | |
|-----------|----------------|
| 1 = spool | L14 |
| 2 = spool | L1 |
| 3 = spool | S2 |
| 4 = spool | L3, S3, D3 |
| 5 = spool | L5, S5, D5, V9 |



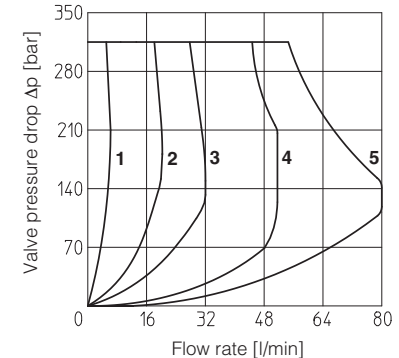
13.3 Bode diagrams

- | |
|------------------------------|
| 1 = 10% ↔ 90% nominal stroke |
| 2 = 50% ± 5% nominal stroke |



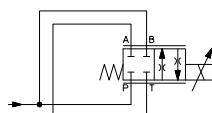
13.4 Operating limits

- | | |
|-----------|----------------|
| 1 = spool | L14 |
| 2 = spool | L1 |
| 3 = spool | S2 |
| 4 = spool | L3, S3, D3 |
| 5 = spool | L5, S5, D5, V9 |



13.5 Operation as throttle valve

Single solenoid valves (DHZO-*-051) can be used as simple throttle valves: Pmax = 250 bar (option /Y advisable)



	SPOOL TYPE						
	L14	L1	S2	L3	S3	L5	S5
Max flow Δp= 70bar [l/min]	6	20	40	80		100	

13.6 Dynamic response

The response times in section 3 and the frequency responses in the bode diagrams have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.

14 DIAGRAMS FOR DKZOR (based on mineral oil ISO VG 46 at 50 °C)

14.1 Regulation diagrams

- 1** = linear spool L3
2 = progressive spool S3, D3
3 = linear spool, zero overlapping OL3
4 = linear spool L5
5 = linear spool, zero overlapping OL5
6 = progressive spool S5, D5
7 = progressive spool, zero overlapping OD5

Note:

Hydraulic configuration vs. reference signal for double solenoid valves (also for option /B)

Reference signal $0 \div +10 \text{ V}$ $12 \div 20 \text{ mA}$ $P \rightarrow A / B \rightarrow T$

Reference signal $0 \div -10 \text{ V}$ $4 \div 12 \text{ mA}$ $P \rightarrow B / A \rightarrow T$

Hydraulic configuration vs. reference signal for mono solenoid valves option /B

Reference signal $0 \div +10 \text{ V}$ $12 \div 20 \text{ mA}$ $P \rightarrow B / A \rightarrow T$

8 = linear spool Q5

Q5 spool type is specific for alternate P/Q controls and it can be used in combination with /S* option of digital integral drivers, see tab. G212, or digital position controllers type Z-RI-TEZ (see tab. G330) or Z-ME-KZ (see tab. G340).

It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers.

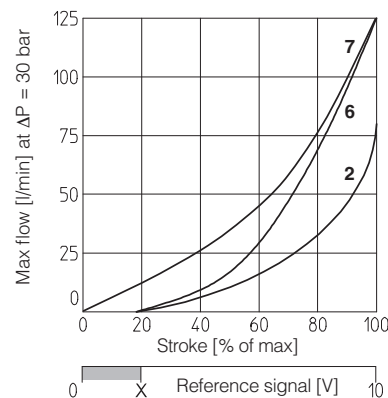
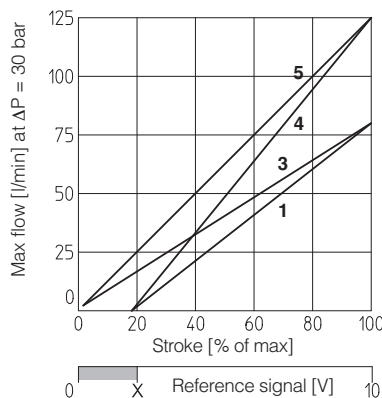
The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.

9 = differential - progressive spool V9

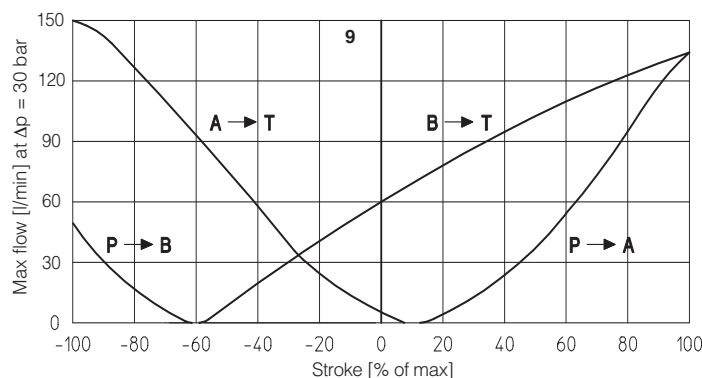
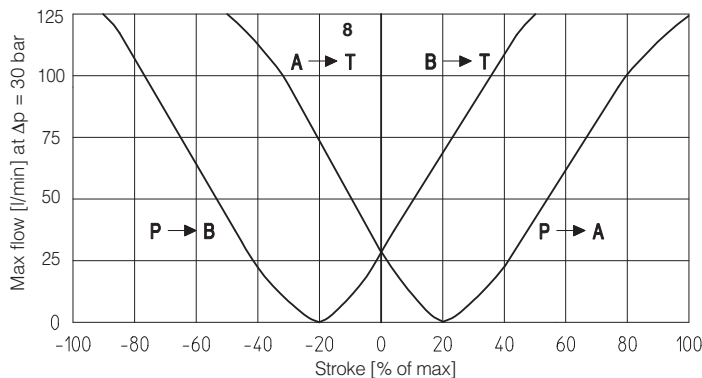
V9 spool type is specific for alternate P/Q controls and it can be used in combination with /S* option of digital integral drivers, see tab. G212, or digital position controllers type Z-RI-TEZ (see tab. G330) or Z-ME-KZ (see tab. G340).

This spool is specially designed to manage the whole injection cycle in plastic machinery, thanks to the following specific features:

- strong meter-in characteristic to allow the pressure control in A port during the holding pressure (P-A) and the plasticizing (A-T) phases
- safety central position (A-T/B-T) to depressurize the actuator chambers
- large A-T and B-T flow capability, required during the plasticizing phase, to discharge big volumes from high differential injection cylinders with low pressure drops and permitting the temporary oil suction from tank



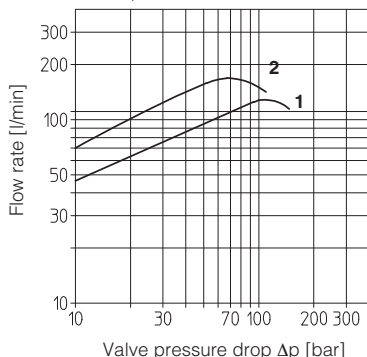
X = Threshold for bias activation depending to the valve type and amplifier type



14.2 Flow /Δp diagrams

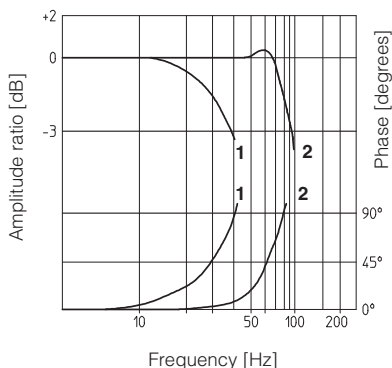
stated at 100% of valve stroke

- 1** = spool S3, L3, D3
2 = spool S5, L5, D5, V9



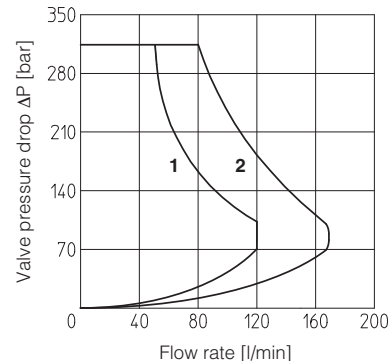
14.3 Bode diagrams

- 1** = 10% ↔ 90% nominal stroke
2 = 50% ± 5% nominal stroke



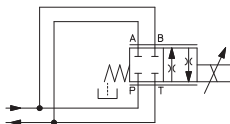
14.4 Operating limits

- 1** = spool L3, S3, D3
2 = spool L5, S5, D5, V9



14.5 Operation as throttle valve

Single solenoid valves (DKZOR*-151) can be used as simple throttle valves: Pmax = 250 bar (option /Y advisable)



	SPOOL TYPE			
	L3	S3	L5	S5
Max flow Δp= 30 bar [l/min]	150		250	

14.6 Dynamic response

The response times in section 3 and frequency responses in the bode diagrams have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.

15 INSTALLATION DIMENSIONS FOR DHZO [mm]

ISO 4401: 2000

Mounting surface: 4401-03-02-0-05 (see table P005)

(for /Y surface 4401-03-03-0-05 without X port)

Fastening bolts: 4 socket head screws M5x50 class 12.9

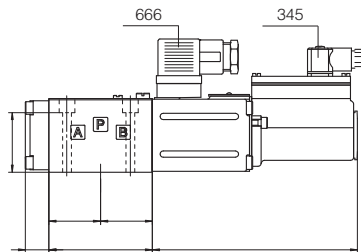
Tightening torque = 8 Nm

Seals: 4 OR 108; 1 OR 2025

Diameter of ports A, B, P, T: Ø 7,5 mm (max)

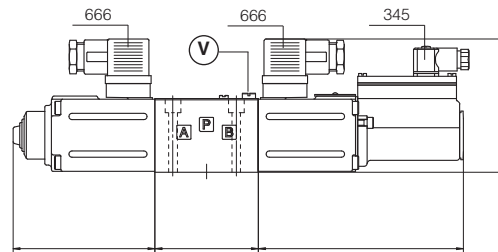
Diameter of port Y: Ø = 3,2 mm (only for /Y option)

DHZO-T-05



Mass: 1,9 kg

DHZO-T-07



Mass: 2,6 kg

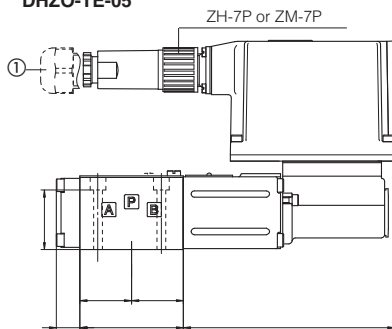
Note: for option /B the solenoid and the position transducer are at side of port A

(V) = Air bleed off

-TE EXECUTION

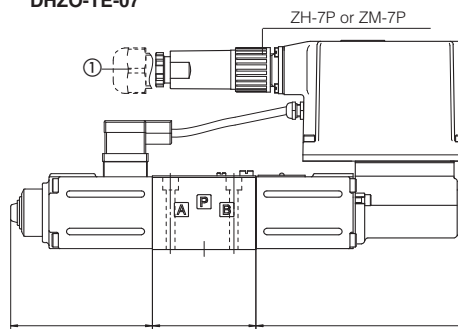
① Dotted line = 12 pin connector ZH-12P for options /K and /Z

DHZO-TE-05



Mass: 2,3 kg

DHZO-TE-07



Mass: 3,1 kg

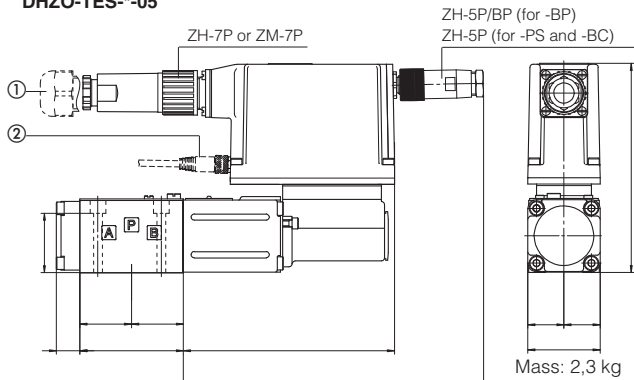
-TES EXECUTION

① Dotted line = 12 pin connector ZH-12P for options /SF, /SL, /SP, /Z

② Dotted line = M8 connector ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)

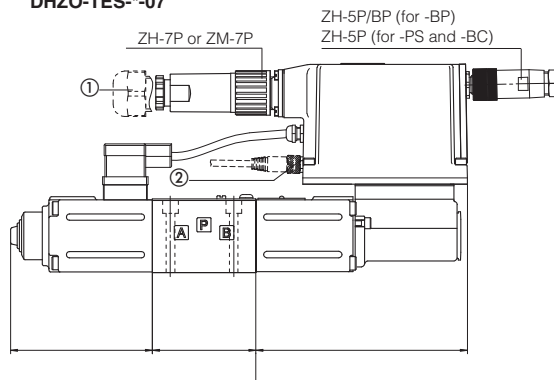
M8 connector ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

DHZO-TES*-05



Mass: 2,3 kg

DHZO-TES*-07



Mass: 3,1 kg

Note: for option /B the solenoid, the position transducer and the integral electronics are at side of port A

16 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

VALVE VERSION	-T		-TE, -TES		-TE /Z -TES /Z, /SF, /SL, /SP	serial (-PS) or CANopen (-BC)	PROFIBUS DP (-BP)	TES /SF, /SL, /SP (transducer)
	Power supply	Transducer						
CONNECTOR CODE	666	345	ZH-7P	ZM-7P	ZH-12P	ZH-5P	ZH-5P/BP	ZH-4P-M8/* (1)
PROTECTION DEGREE	IP65	IP65	IP67	IP67	IP67	IP67	IP67	IP67
DATA SHEET	K500		G200, G210, K500			G210, K500		G212, K500

(1) M8 connector ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)

M8 connector ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

connectors supplied with the valve

17 INSTALLATION DIMENSIONS FOR DKZOR [mm]

ISO 4401: 2000

Mounting surface: 4401-05-04-0-05 (see table P005)

(for /Y surface 4401-05-05-0-05 without X port)

Fastening bolts: 4 socket head screws M6x40 class 12.9

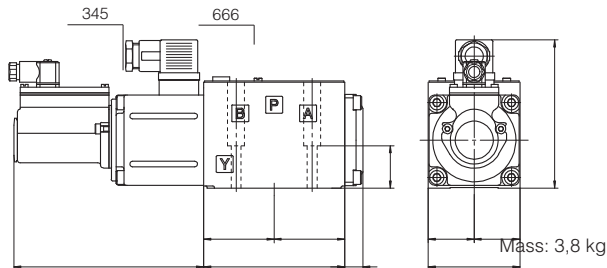
Tightening torque = 15 Nm

Seals: 5 OR 2050; 1 OR 108

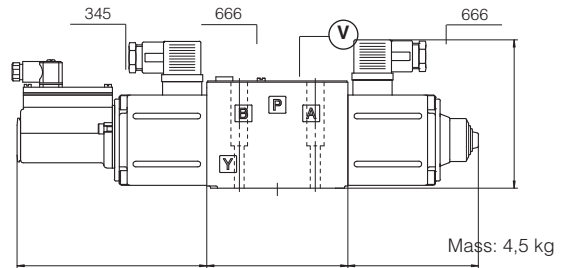
Diameter of ports A, B, P, T: Ø 11,2 mm (max)

Diameter of port Y: Ø = 5 mm (only for /Y option)

DKZOR-T-15



DKZOR-T-17



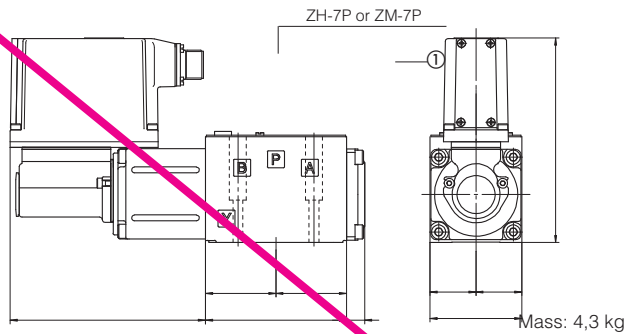
Note: for option /B the solenoid and the position transducer are at side of port A

Ⓥ = Air bleed off

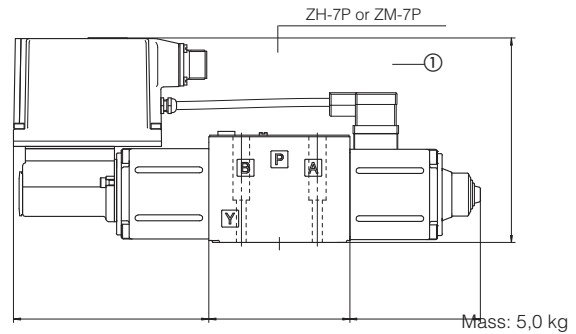
-TE EXECUTION

① Dotted line = 12 poles connector ZH-12P for options /K and /Z

DKZOR-TE-15



DKZOR-TE-17

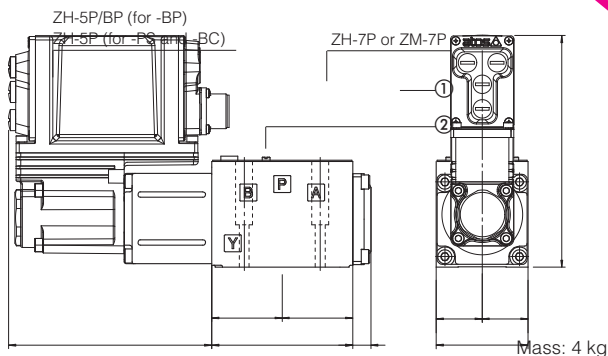


-TES EXECUTION

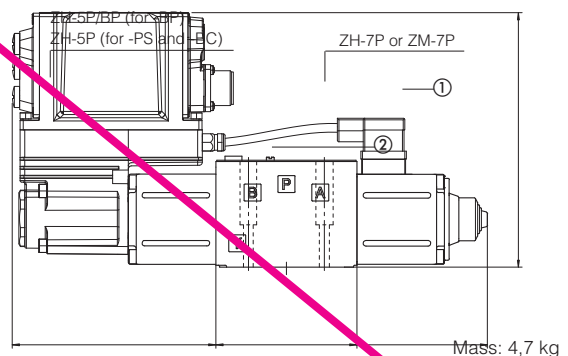
① Dotted line = 12 pin connector ZH-12P for options /SF, /SL, /SP, /Z

② Dotted line = M8 connector ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)
M8 connector ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

DKZOR-TES*-15



DKZOR-TES*-17



Note: for option /B the solenoid, the position transducer and the integral electronics are at side of port A

18 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

VALVE VERSION	-T		-TE, -TES		-TE /Z -TES /Z, /SF, /SL, /SP	serial (-PS) or CANopen (-BC)	PROFIBUS DP (-BP)	TES /SF, /SL, /SP (transducer)
CONNECTOR CODE	Power supply 666	Transducer 345	ZH-7P	ZM-7P	ZH-12P	ZH-5P	ZH-5P/BP	ZH-4P-M8/* (1)
PROTECTION DEGREE	IP65	IP65	IP67	IP67	IP67	IP67	IP67	IP67
DATA SHEET	K500		G200, G210, K500			G210, K500		G212, K500

(1) M8 connector ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)

M8 connector ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

connectors supplied with the valve